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REISSUE PATENT APPLICATION TRANSMITTAL

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	Attorney Docket No.	MTS-880US2			
Address to: PROPONICO REIGHUE	First Named Inventor	Thiow Keng Tan			
Assistant Commissioner for Patents	Original Patent Number	5,825,421			
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APPLICATION FOR REISSUE OF: (check applicable box) Utility F	atent Design Pa	atent Plant Patent			
APPLICATION ELEMENTS	ACCOMPANYING	APPLICATION PARTS			
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2. X Specification and Claims (amended, if appropriate)	8. Information Disclo Statement (IDS)/F				
3. X Drawing(s) (proposed amendments, if appropriate)	9. English Translatio	n of Reissue Oath/Declaration			
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6. Original U.S. Patent currently assigned?					
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CERTIFICATE OF I	Docket No. Substitution of the Docket No. MTS-880US2			
Serial No. To Be Assigned	Examiner	Group Art Unit		
Invention: VIDEO COD	DING METHOD AND DECODIN	NG METHOD AND DEVICES THE	REOF	
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VIDEO CODING METHOD AND DECODING METHOD AND DEVICES THEREOF

BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention can be used in low bit rate video coding for tele-communicative applications. It improves the temporal frame rate of the decoder output as well as the overall picture quality.

2. Related art of the Invention

In a typical hybrid transform coding algorithm such as the ITU-T Recommendation H.261 [1] and MPEG [2] motion compensation is used to reduce the amount of temporal redundancy in the sequence. In the H.261 coding scheme, 15 the frames are coded using only forward prediction, hereafter referred to as P-frames. In the MPEG coding scheme, some frames are coded using bi-direction prediction, hereafter referred to as B-frames. B-frames improve the efficiency of the coding scheme. Now the [1] is ITU-T Recommendation H.261 (Formerly CCTIT Recommendation H.261) Codes for audiovisual services at px64 kbit/s Geneva, 1990, and the [2] is ISO/IEC 11172-2 1993. Information technology—Coding of moving pictures and associated audio for digital storage media at up to about 1.5 25 Mbit/s - Part 2: Video.

However, it introduces delay in the encoding and decoding, making it unsuitable for applications in the communicative services where delay is an important parameter. FIG. 1a and 1b illustrates the frame prediction of H.261 and MPEG as described above. A new method of coding involving the coding of the P and B frames as a single unit, hereafter referred to as the PB-frame, was introduced. In this scheme the blocks in the PB-frames are coded and transmitted together thus reducing the total delay. In fact the total delay should not be more than a scheme using forward prediction only but at half the frame rate.

FIG. 2a shows the PB-frame prediction. A PB-frame consists of two pictures being coded as one unit. The name PB comes from the name of picture types in MPEG where there are P-frames and B-frames. Thus a PB-frame consists of one P-frame which is predicted from the last decoded P-frame and one B-frame which is predicted both from the last decoded P-frame and the P-frame currently being decoded. This last picture is called B-frame because parts of it may be bi-directionally predicted from the past and future P-frame.

FIG. 2b shows the forward and bi-directional prediction for a block in the B-frame, hereafter referred to as a B-block. Only the region that overlaps with the corresponding block in the current P-frame, hereafter referred to us the P-block is bi-directionally predicted. The rest of the B-block is forward predicted from the previous frame. Thus only the previous frame is required in the frame store. The information from the P-frame is obtained from the P-block currently being decoded.

In the PB-block only the motion vectors for the P-block is transmitted to the decoder. The forward and backward motion vectors for the B-block is derived from the P motion so vectors. A linear motion model is used and the temporal reference of the B and P trame is used to scale the motion vector appropriately. FIG. 3a depicts the motion vector scaling and the formula is shown below

ن MVVTR نتي ۱۱۷ سے ۱۱۷

,t, 25

where

MV is the motion vector of the P-block.

 MV_F and MV_B are the forward and backward motion vectors for the B-block.

 TR_g is the increment in the temporal reference from the last P-frame to the current B-frame, and

TR_p is the increment in the temporal reference from the last P-frame to the current P-frame.

Currently the method used in the prior art assumes a linear motion model. However this assumption is not valid in a normal scene where the motion is typically not linear. This is especially true when the camera shakes and when objects are not moving at constant velocities.

A second problem involves the quantization and transmission of the residual of the prediction error in the B-block Currently the coefficients from the P-block and the B-block are interleaved in some scanning order which requires the B-block efficients to be transmitted even when they are all zero. This is not very efficient as it is quite often that there are no residual coefficients to transmit (all coefficients are

SUMMARY OF THE INVENTION

25 In order to solve the first problem, the current invention employs a delta motion vector to compensate for the nonlinear motion. Thus it becomes necessary for the encoder to perform an additional motion search to obtain the optimum delta motion vector that when added to the derived motion vectors would result in the best match in the prediction This delta motion vectors are transmitted to the decoder at the block level only when necessary. A flag is used to indicate to the decoder if there are delta motion vectors present for the B-block.

For the second problem, this invention also uses a flag to indicate if there are coefficients for the B-block to be decoded.

The operation of the Invention is described as follows.

40 FIG. 3a shows the linear motion model used for the derivation of the forward and backward motion vectors from the P-block motion vector and the temporal reference information As illustrated in FIG. 3b. this model breaks down when the motion is not linear. The derived forward and backward motion vector is different from the actual motion vector when the motion is not linear. This is especially true when objects in the scene are moving at changing velocities.

In the current invention the problem is solved by adding a small delta motion vector to the derived motion vector to compensate for the difference between the derived and true motion vector. Therefore the equations in (1) and (2) are now replaced by equations (3) and (4), respectively.

$$MV_{e} = TR_{g} \cup MVVTR_{e} - MV_{Option}$$
 (3)

$$MV_{g} = (TR_{g} - TR_{p} \times MVVTR_{p} - MV_{Optio})$$
(4)

where

MV is the motion vector of the P-block.

MV Delta is the delta motion vector.

MV's' and MV's' are the new forward and backward motion vectors for the B-block according to the current invention.

 TR_B is the increment in the temporal reference from the last P-frame to the current B-frame, and

TR_p is the increment in the temporal reference from the last P-trame to the current P-trame.

Note: Equations (3) and (4) are used for the motion vector in the horizontal as well as the vertical directions. Thus the motion vectors are in pairs and there are actually two independent delta motion vectors, one each for the horizontal and vertical directions.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1a is a prior art which illustrates the prediction mode used in the ITU-T Recommendation H.261 Standard.

FIG. 1b is a prior art which illustrates the prediction mode used in the ISO-IEC/ITC MPEG Standard.

FIG. 2a illustrates the PB-frame prediction mode.

FIG. 2b illustrates the B-block bi-directional prediction mode.

FIG. 3a illustrates the linear motion model.

FIG. 3b illustrates the non-linear motion model of the current invention

FIG. 4 illustrates the encoder functionality block diagram. x

FIG. 5 illustrates the B-block bi-directional prediction functionality block diagram.

FIG. 6 illustrates the decoder functionaltity block diagram.

PREFERRED EMBODIMENTS

2:

The preferred embodiment of the current invention is described here. FIG. 4 illustrates the encoding functionality diagram. The present invention deals with the method for deriving the motion vectors for the B-block. The encoding functionality is presented here for completeness of the embodiment.

The encoding functionality block diagram depicts an encoder using a motion estimation and compensation for reducing the temporal redundancy in the sequence to be coded. The input sequences is organized into a first frame and pairs of subsequent frames. The first frame, hereafter referred to as the I-frame, is coded independent of all other frames. The pairs of subsequent frames, hereafter referred to as PB-frame, consist of a B-frame followed by a P-frame. The P-frame is forward predicted based on the previously reconstructed I-frame or P-frame and the B-frame is bi-directionally predicted based on the previously reconstructed I-frame or P-frame and the information in the current P-frame.

The input frame image sequence. 1. is placed in the Frame Memory 2. If the frame is classified as an I-frame or a P-frame it is passed through line 14 to the Reference Memory 3. for use as the reference frame in the motion 5 estimation of the aext PB-frame to be predictively encoded. The signal is then passed through line 13 to the Block Sampling module 4, where it is partitioned into spatially non-overlapping blocks of pixel data for further processing.

If the frame is classified as an I-frame, the sampled blocks are passed through line 16 to the DCT module 7. If the frame is classified as a PB-frame, the sampled blocks are passed through line 17 to the Motion Estimation module 5. The Motion Estimation module 5 uses information from the Reference Frame Memory 3 and the current block 17 to eobtain the motion vector for that provides the best match for the P-block The motion vector and the local reconstructed frame. 12, are passed through line 19 and 20, respectively, to the Motion Compensation module 6. The difference image is formed by subtracting the motion compensated decoded frame. 21, from the current P-block, 15. This signal is then passed through line 22 to the DCT module 7.

In the DCT module 7, each block is transformed into the DCT domain coefficients. The transform coefficients are passed through line 23 to Quantization module 8, where they are quantized. The quantized coefficients are then passed through line 24 to the Run-length & Variable Length Coding module 9. Here the coefficients are entropy coded to form the Output Bit Stream. 25.

If the current block is an I-block or a P-block, the quantized coefficients are also passed through line 26 to the Inverse Quantization module 10. The output of the Inverse Quantization 10, is then passed through line 27 to the Inverse DCT module 11. If the current block is an I-block then the reconstructed block is placed, via line 28, in the Local Decoded Frame Memory 12. If the current block is a P-block then the output of the Inverse DCT 29 is added to the motion compensated output 21, to from the reconstructed block 30. The reconstructed block 30, is then placed in the Local Decoded Frame Memory 12, for the motion compensation of the subsequent frames.

After the P-block have been locally reconstructed, the information is passed again to the Motion Compensation Module 6, where the prediction of the B-block is formed. FIG. 5 shows a more detailed functional diagram for the B-block prediction process. The P-motion vector derived in the Motion Estimation module 51, is passed through line 57 to the Motion Vector Scaling Module 53. Here the forward and backward motion vectors of the B-block is derived using 30 the formula (1) and (2), respectively. In the present embodiment, an additional motion search around these vectors is performed in the Delta Motion Search module 54. to obtain the delta motion vector. In this embodiment the motion vector is obtained by performing the search for all delta motion vector values between -3 and 3. The delta motion vector value that gives the best prediction in terms of the smallest mean absolute difference in the pixel values of the B-block and the prediction block is chosen. The predic-40 tion is formed in the Bi-directional Motion Compensation module 55, according to FIG. 2b using the information from the Local Decoded Frame Memory 52, and the Current Reconstructed P-block 50. In the bi-directional prediction. only information available in the corresponding P-block is 45 used to predict the B-block. The average of the P-block information and the information from the Local Decoded Frame is used to predict the B-block. The rest of the B-block is predicted using information from the Local Decoded 50 Frame only.

The prediction difference block is then passed through line 22 to the DCT module 7. The DCT coefficients are then passed through line 23 to the Quantization module 8. The result of the Quantization module 8, is passed through line 55 24 to the Run-length & Variable Length Coding 9. In this module the presence of the delta motion vector and the quantized residual error in the Output Bitstream 25, is indicated a variable length code. NOB which is the acronym for No B-block This flag is generated in Run-leagth & 60 Variable Length Coding module 9 based on whether there are residual error in the Quantization module 8 and delta motion vectors found in the Delta Motion Search module 54 is not zero. Table I provides the preferred embodiment of the variable length code for the NOB flag. The variable length 65 code of the NOB flag is inserted in the Output Bitstream. 25. prior to the delta motion vector and quantized residual error codes.

TABLE I

(Vanable length code for the NOB flag)				
NOB	Quantized Residual Error Coded	Delta Motica Vectors Coded	5	
0	No	No		
10	No	Yes		
110	Yes	No		
111	Yes	Yes	10	

FIG. 6 shows the functional block diagram for the decoder. The Input Bit Stream 31. is passed to the Variable Length & Run Length Decoding module 32. The block and side information are extracted in this module. If the frame is a PB-frame then the bitstream is checked if any delta motion vector and/or quantized residual error coefficients present. The output of the module 32 is passed through line 37 to the Inverse Quantization module 33. The output of the Inverse Quantization 33. is then passed through line 38 to the Inverse DCT module 34. Here the coefficients are transformed back into the pixel values.

If the current frame is an I-frame then the output of Inverse DCT 34, is passed through line 39 and stored in the Frame Memory 42.

If the current frame is a PB-frame, the side information containing the motion vectors are passed through line 45 to the Motion compensation module 36. The motion Compensation module 36, uses this information and the information in the Local Decoded Memory. 35, to from the motion compensated signal, 44. This signal is then added to the output of the Inverse DCT module 34, to form the reconstruction of the P-block.

The Motion Compensation module 36, then uses the additional information obtained in the reconstructed P-block to obtain the bi-directional prediction for the B-block. The B-block is then reconstructed and placed in the Frame Memory, 42, together with the P-block.

By implementing this invention, the temporal frame rate 40 of the decoded sequences can be effectively doubled at a fraction of the expected cost in bit rate. The delay is similar to that of the same sequence decoded at half the frame rate.

As described above in the present invention a new predictive coding is used to increase the temporal frame rate 45 and coding efficiency without introducing excessive delay. Currently the motion vector for the blocks in the bi-directionally predicted frame is derived from the motion vector of the corresponding block in the forward predicted frame using a linear motion model. This however is not 50 effective when the motion in the image sequence is not linear. According to this invention, the efficiency of this method can be further improved if a non-linear motion model is used. In this model a delta motion vector is added to or subtracted from the derived forward and backward 55 motion vector, respectively. The encoder performs an additional search to determine if there is a need for the delta motion vector. The presence of this delta motion vector in the transmitted bustream is signalled to the decoder which then takes the appropriate action to make use of the delta 60 motion vector to derive the effective forward and backward motion vectors for the bi-directionally predicted block What is claimed:

1. A method for encoding a sequence of video image frames comprising the steps of

dividing a source sequence into a set of group of pictures. each group of pictures comprising a first frame

(I-frame) followed by a plurality of pairs of predictively encoded frames (PB-frame pairs), each PB-frame pair having a corresponding P-block:

- dividing each I-frame or PB-frame pair into a plurality of spatially non-overlapping blocks of pixel data:
 - encoding the blocks from the I-frame (I-blocks) independently from any other frames in the group of pictures;
 - predictively encoding the blocks from the second frame of the PB-frame pair (P-blocks), based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair:
 - bi-directionally predictively encoding the blocks from the first frame of the PB-frame pair (B-blocks), based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair and the corresponding P-block in the current PB-frame pair:
 - deriving a scaled forward motion vector and a scaled backward motion vector for the B-block by scaling the motion vector of the corresponding P-block in the current PB-frame pair:
 - obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector: and
- obtaining a final backward motion vector for the B-block by subtracting the delta motion vector from the scaled backward motion vector.
- 2. A method for encoding a sequence of video image frames according to claim 1. wherein
 - the scaling of the motion vector is based on a temporal reference of the first and second frames of the PB-frame pair.
- 3. A method for encoding a sequence of video image frames according to claim 1. further comprising the step of forming an encoded output, wherein the encoded output is a bitstream comprising:

temporal reference information for the first and second frames of the PB-frame pairs:

- motion vector information for the P-blocks:
 - quantized residual error information for the P-blocks:
 - delta motion vector information for the B-blocks; and quantized residual error information for the B-blocks.
- 4. A method for encoding a sequence of video image frames according to claim 3, wherein
 - the output bitstream contains additional information to indicate the presence of at least one of:
 - the delta motion vector information for the B-blocks; and
- the quantized residual error information for the B-blocks.
 - 5. A method for decoding a sequence of video image frames comprising the steps of:
 - decoding the compressed video image sequence as a set of group of pictures, each group of pictures comprising an I-frame followed by a plurality of PB-trame pairs, each PB-frame pair having a corresponding P-block:
 - decoding each I-frame or PB-frame pair into a plurality of spatially non-overlapping blocks of pixel data:
- decoding the I-blocks from the I-frame independently from any other frames in the group of pictures:
 - predictively decoding the P-blocks from the second frame of the PB-frame pair based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair:
 - bi-directionally predictively decoding the B-blocks from the first frame of the PB-frame pair based on the

I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair and the corresponding P-block in the current PB-frame pair;	
deriving a scaled forward motion vector and a scaled backward motion vector for the B-block by scaling the motion vector of the corresponding P-block in the current PB-frame pair:	5
obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector; and	t0
obtaining a final backward motion vector for the B-block by subtracting the delta motion vector from the scaled backward motion vector.	
6. A method for decoding a sequence of video image frames according to claim 5. further comprising the step of forming a decoded output, wherein the decoded output is responsive to a bitstream comprising:	15
temporal reference information for the first and second frames of the PB-frame pairs:	20
motion vector information for the P-blocks: quantized residual error information for the P-blocks: the delta motion vector information for the B-blocks: and	-
quantized residual error information for the B-blocks. 7. A method for decoding a sequence of video image frames according to claim 6. wherein	25
the bitstream contains additional information to indicate the presence of at least one of:	
the delta motion vector information for the B-blocks; and the quantized residual error information for the B-blocks. 8. A method of decoding a sequence of video image frames according to claim 5, wherein	30
the scaling is based on a temporal reference of the first and second frames of the PB-frame pair. 9. An apparatus for encoding a sequence of video image frames comprising:	35
means for encoding each frame in a sequence of video image frames into a set of group of pictures, each group of pictures comprising an I-frame followed by a plurality of PB-frame pairs:	40
means for dividing the I-frame and the PB-frame pair into a plurality of spatially non-overlapping blocks of pixel data:	
means for encoding and decoding the I-blocks of the I-frame independently from any other frames in the group of pictures:	45
means for storing the decoded I-blocks to predictively encode subsequent frames:	5C
means for predictively encoding and decoding the P-blocks of the second frame of the PB-frame pair based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair:	
means for storing the decoded P-blocks to predictively encode subsequent frames:	\$5
means for deriving a scaled forward motion vector and a scaled backward motion vector for a B-block by scaling the motion vector of the corresponding P-block in the current PB-trame pair, the B-block being the first frame of the PB-trame pair:	6C
means for obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector:	
means for obtaining a final backward motion vector for the B-block by subtracting the same delta motion vector from the scaled backward motion vector; and	63

means for encoding the B-blocks of the first frame of the PB-frame pairs based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair and the corresponding P-block in the current PB-frame pair using the final forward motion vector and the final backward motion vector.

10. An apparatus for decoding a sequence of video image frames comprising:

means for decoding each frame in a sequence of video image frames into a set of group of pictures, each group of pictures comprising an I-frame followed by a plurality of PB-frame pairs:

15

25

- means for decoding the I-blocks of the I-frame independently of any other frames in the group of pictures:
- means for storing the decoded I-blocks to predictively decode subsequent frames:
- . means for decoding the P-blocks of the second frame of the PB-frame pair based on the I-blocks in the previous I-frame or the P-blocks in the previous PB-frame pair;
- means for storing the decoded P-blocks to predictively decode subsequent frames:
- means for deriving a scaled forward motion vector and a scaled backward motion vector for a B-block by scaling the motion vector of the corresponding P-block in the current PB-frame pair, the B-block being the first frame of the PB-frame pair:
- means for obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector:
 - means for obtaining a final backward motion vector for the B-block by subtracting the delta motion vector to the scaled backward motion vector; and
- means for decoding the B-blocks of the first frame of the PB-frame pairs based on the I-blocks in the previous I-frame of the P-blocks in the previous PB-frame pair and the corresponding P-block in the current PB-frame pair using the final forward motion vector and the final backward motion vector.
 - 11. A method for encoding a sequence of video image frames comprising the steps of:
- dividing a source sequence into a plurality of groups of pictures, each group of pictures comprising a first frame (I-frame) followed by a plurality of pairs of predictively encoded frames (PB-frame pairs):
 - dividing each I-frame or PB-frame pair into a plurality of blocks:
- encoding the blocks from the I-frame:
 - predictively encoding the blocks from the second frame of the PB-frame pair:
 - bi-directionally predictively encoding the blocks from the first frame of a PB-frame pair (B-blocks):
- deriving a scaled forward motion vector and a scaled backward motion vector for the B-block:
 - obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector; and
 - obtaining a final backward motion vector for the B-block by subtracting the delta motion vector from the scaled backward motion vector.
- 12. An apparatus for encoding a sequence of video image 65 frames comprising:
 - means for dividing a source sequence into a plurality of groups of pictures, each group of pictures comprising a

first frame (I-frame) followed by a plurality of pairs of predictively encoded frames (PB-frame pairs):

means for dividing each I-frame or PB-frame pair into a plurality of blocks:

means for encoding the blocks from the I-frame:

means for predictively encoding the blocks from the second frame of the PB-frame pair;

means for bi-directionally predictively encoding the blocks from the first frame of a PB-frame pair (B-blocks);

means for deriving a scaled forward motion vector and a scaled backward motion vector for the B-block:

means for obtaining a final forward motion vector for the B-block by adding a delta motion vector to the scaled forward motion vector; and

means for obtaining a final backward motion vector for the B-block by subtracting the delta motion vector from the scaled backward motion vector.

_ _ _

1	13. A method for decoding a
2	compressed video image sequence of a
3	group of pictures including an I-frame
4	followed by a plurality of P-frames and B-
5	frames, comprising the steps of:
6	decoding a block in the I-
	
7	frame independently from any other frames
8	in the group of pictures;
9	predictively decoding a block
10	in a P-frame based on the previous I-frame
11	or a previous P-frame;
12	bi-directionally predictively
13	decoding a block in a B-frame based on the
14	previous I-frame or a previous P-frame and
15	a block in a P-frame positioned after the B-
16	frame;
17	deriving a scaled forward
18	motion vector and a scaled backward motion
19	vector for the block in the B-frame by
20	scaling a motion vector of the block in the
21	P-frame positioned after the B-frame;
22	obtaining a final forward
23	motion vector for the block in the B-frame
24	by adding a delta motion vector to the scaled
25	forward motion vector, and

26	obtaining a final backward
27	motion vector for the block in the B-frame
28	by adding the delta motion vector to the
29	scaled backward motion vector.
,	14 A mathad of docading a
1	14. A method of decoding a
2	sequence of video image frames according
3	to claim 13, wherein the deriving step
4	includes:
5	scaling of the forward and
6	backward motion vectors is based on a
7	temporal reference of the B-frame and the P-
8	frame.
1	15. A method for decoding a
2	sequence of video image frames according
3	to claim 13, further comprising the step of
4	forming a decoded output, wherein the
5	decoded output is responsive to a bitstream
6	comprising:
7	temporal reference
8	information for the B-frame and the P-
9	frame;
10	motion vector information for
11	the block in the P-frame;
	THE CLOSE AND IN LAND I MILLION
12	quantized residual error
13	information for the block in the P-frame;

14	the delta motion vector
15	information for the block in the B-frame;
16	and
17	quantized residual error
18	information for the block in the B-frame.
1	16. A method for decoding a
	<u> </u>
2	sequence of video image frames according
3	to claim 15, wherein
4	the bitstream contains
5	additional information indicating a presence
6	of at least one of
7	the delta motion vector
8	information for the block in the B-frame;
9	and
10	the quantized residual error
10	
11	information for the block in the B-frame.



United States Patent [19]

Tan

[56]

Patent Number: [11]

5,825,421

Date of Patent: [45]

Oct. 20, 1998

OTHER PUBLICATIONS

Secretariat: Japan (JISC), "Coded Representation of Audio, Picture, Multimedia and Hypermedia Information," ISO/ IEC JTC 1/SC 29 N 313. dated May 20. 1993.

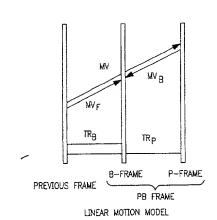
"Recommendation H.261-Video Codec for Audiovisual Services at px 64 kbit/s". International Telegraph and Telephone Consultative Committee. Study Group XV-Report R 37, Aug. 1990.

Primary Examiner-Tommy P. Chin Assistant Examiner-Tung Vo Attorney, Agent, or Firm-Ratner & Prestia

ABSTRACT

A new predictive coding is used to increase the temporal frame rate and coding efficiency without introducing excessive delay. Currently the motion vector for the blocks in the bi-directionally predicted frame is derived from the motion vector of the corresponding block in the forward predicted frame using a linear motion model. This however is not effective when the motion in the image sequence is not linear. The efficiency of this method can be further improved if a non-linear motion model is used. In this model a delta motion vector is added to or subtracted from the derived forward and backward motion vector, respectively. The encoder performs an additional search to determine if there is a need for the delta motion vector. The presence of this delta motion vector in the transmitted bitstream is signalled to the decoder which then takes the appropriate action to make use of the delta motion vector to derive the effective forward and backward motion vectors for the bi-directionally predicted block.

12 Claims, 6 Drawing Sheets



[54]		ODING METHOD AND DECODING AND DEVICES THEREOF
[75]	Inventor:	Thiow Keng Tan. Singapore. Singapore
[73]	Assignee:	Matsushita Electronic Industrial Co., Ltd Osaka. Japan
[21]	Appl. No.:	773,574
[22]	Filed:	Dec. 27, 1996
[30]	Forei	gn Application Priority Data
Dec.	27, 1995	[JP] Japan 7-340609
		H04N 7/32
[52]	U.S. Cl	348/409 ; 348/413; 348/415;
		348/699

References Cited

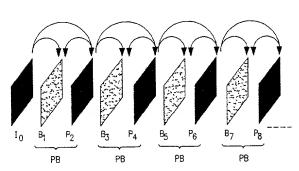
Field of Search

U.S. PATENT DOCUMENTS

348/415, 396, 416, 699, 402; 382/56; H04N 7/32

.. 348/409, 413,

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5,386,234	1/1995	Veltman et al
5,412,428	5/1995	Tahara 348/396
5.481,310	1/1996	Hibi



PB FRAME PREDICTION

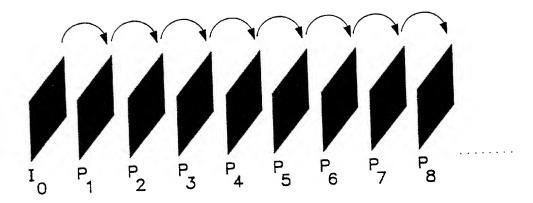


FIG. IA PRIOR ART (H.261)

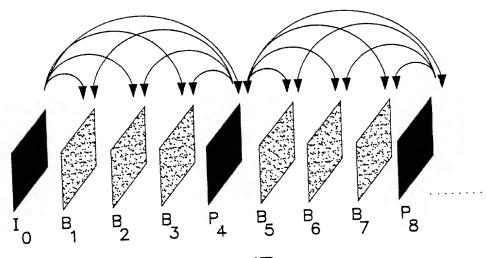
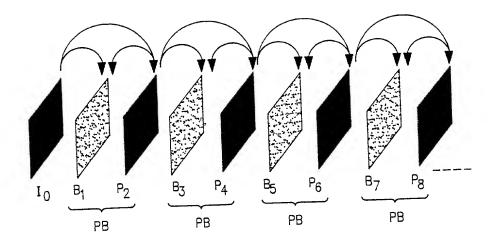


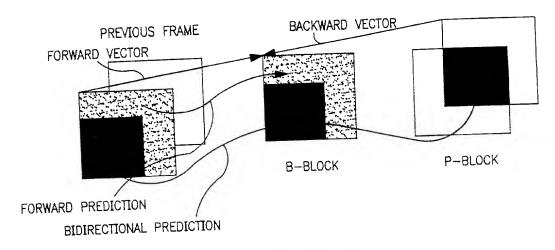
FIG. IB

PRIOR ART (MPEG)



PB FRAME PREDICTION

FIG. 2A



B-BLOCK PREDICTION

FIG. 2B

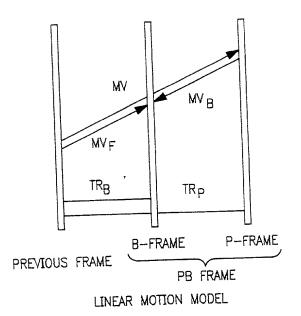
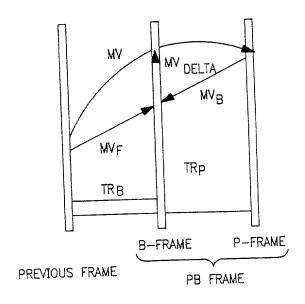


FIG. 3A



NON-LINEAR MOTION MODEL

FIG. 3B

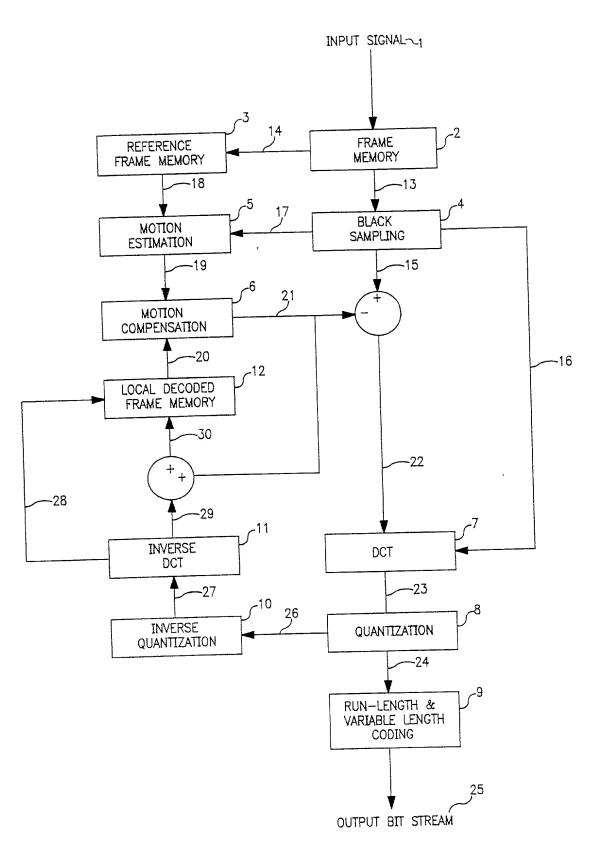
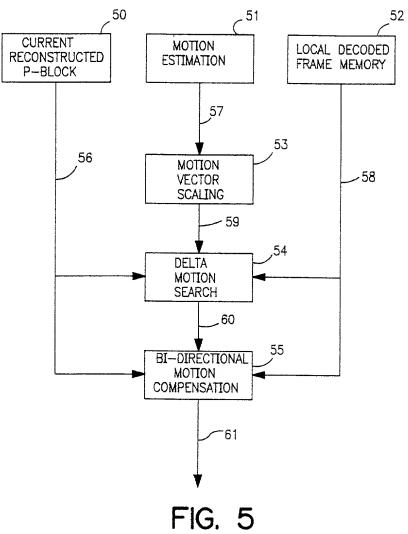


FIG. 4



ŭ m H Z

Docket Number (Optional) REISSUE APPLICATION DECLARATION BY THE INVENTOR MTS-880US2 As a below named inventor, I hereby declare that: My residence, post office address and citizenship are stated below next to my name. I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first

and joint inventor (if plural names are listed below) of the subject matter which is described and claimed October 20, 1998 5,825,421 , granted_ , and for which a reissue patent is sought on the invention entitled VIDEO CODING METHOD AND DECODING METHOD AND DEVICES THEREOF the specification of which is attached hereto. was filed on as reissue application number / and was amended on (Ifapplicable) I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above. I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR 1.56. I verily believe the original patent to be wholly or partly inoperative or invalid, for the reasons described below. (Check all boxes that apply.) by reason of a defective specification or drawing. x by reason of the patentee claiming more or less than he had the right to claim in the patent. by reason of other errors. At least one error upon which reissue is based is described as follows: During the prosecution of the application that issued as the above patent, the inventors did not

recognize that the features disclosed in new claims 13-16 were appropriate to claim. As such, the inventors did not claim all that they had a right to claim. This error was made without deceptive intent.

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(REISSUE APPLICATION DECLARATION BY THE INVENTOR, page 2) Docket Number (Optional) MTS-880US2					
All errors corrected in this reissue application arose without any deceptive intention on the part of the applicant. As a named inventor, I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and transact all business in the Patent and Trademark Office connected therewith.					
Name(s)	Registration Num	nber			
Allan Ratner	1	9,717			
Jack J. Jankovitz	z 4	2,690			
Correspondence A	Address: Direct all communications about	t the applic ation to:			
Customer Nu	umber		Place Cu Code Lai	istomer Number Bar hel here	
OR	Type Customer Number he	ere		Del fiere	
Firm or Individual Name	Ratner & Prestia				
Address	P.O. Box 980				
Address					
City	Valley Forge	State P	PA	ZIP 19482	
Country					
Telephone	(610) 407-0700	Fax ((610) 407-0	701	
knowledge that will or both, under 18 L application, any pa	d belief are believed to be true; and further liful false statements and the like so made U.S.C. 1001, and that such willful false statent issuing thereon, or any patent to white	e are punishable by fil atements may jeopar ich this declaration is	ine and impris	sonment,	
Full name of sole of	r first inventor (given name, family name)	Thiow Keng Tan			
Inventor's signature)	Thiow Items I wil			
Residence Singar	pore	Date			
	S Block 553, Choa Chu Kang North 6, #11-08	Citizenship Mole			
Singapore 2368 Full name of second	d joint inventor (given name, family name	Mala ∍)	iysia		
		,			
Inventor's signature	,	Date			
Residence		Citizenship			
Post Office Address	S				
Full name of third jo	oint inventor (given name, family name)		<u> </u>		
Inventor's signature)	Date	 		
Residence		Citizenship			
Post Office Address	S				
Additional joint inventors are named on separately numbered sheets attached hereto.					

DECLARATION

REGISTERED PRACTITIONER INFORMATION (Supplemental Sheet)

Name	Registration Number	Name	Registration Number
Paul F. Prestia	23,031		
Andrew L. Ney	20,300		
Kevin R. Casey	32,117		
Benjamin E. Leace	33,412		
James C. Simmons	24,842	·	
Lawrence E. Ashery	34,515		
Christopher R. Lewis	36,201		
Robert L. Andersen	25,771		
Daniel N. Calder	27,424		
Louis W. Beardell, Jr.	40,506		
Jacques L. Etkowicz	41,738		
Jonathan H. Spadt	45,122		
Mark J. Marcelli	38,040		
Joshua L. Cohen	42,690		
Jack J. Jankovitz	34,608		
Kevin W. Goldstein	42,621		
Christopher I. Halliday	26,277		
Paul D. Golian	33,602		
William P. Hauser	41,712		
Bruce M. Monroe	28,028		
Rex A. Donnelly, IV	42,866		
Costas Krikelis			
	:		

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REISSUE APPLICATION DECLARATION BY	THE ASSIGNEE Docket Number (optional) MTS-880US2			
I hereby declare that:	1122 33302			
My residence and post office address and citizenship at	re stated below next to my name.			
I am authorized to act on behalf of the following assigne	e: Matsushita Electric Industrial Co., Ltd.			
and the title of my position with said assignee is: Direct	or			
The entire title to the patent identified below is vested in				
Name of Patentee(s):				
Thiow Keng Tan				
Patent Number 5,825,421	Date of Patent Issued October 20, 1998			
Title of Invention	000001 20, 1220			
VIDEO CODING METHOD AND D	ECODING METHOD AND DEVICES THEREOF			
I believe said patentee(s) to be the original, first and so	le/joint inventor(s) of the subject matter which is			
described and claimed in said patent, for which a reissu				
VIDEO CODING METHOD AND DECODING MET	THOD AND DEVICES THEREOF			
the specification of which				
X is attached hereto.				
was filed on as reissue ap	plication number			
(If applicable)				
I have reviewed and understand the contents of the ab amended by any amendment referred to above.				
I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR 1.56.				
I verily believe the original patent to be wholly or partly below. (Check all boxes that apply.)	inoperative or invalid, for the reasons described			
by reason of a defective specification or drawing].			
x by reason of the patentee claiming more or less than he had the right to claim in the patent.				
by reason of other errors.				
At least one error upon which reissue is based is desc	ribed as follows:			
During the prosecution of the application that issued a the features disclosed in new claims 13-16 were approall that they had a right to claim. This error was made	as the above patent, the inventors did not recognize that opriate to claim. As such, the inventors did not claim e without deceptive intent.			
[Attach additional st	neets, if needed.]			
All errors corrected in this reissue application arose was applicant.	thout any deceptive intention on the part of the			

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MTS-880US2												
I hereby appoint all business in th Name(s) Allan Ratner	ne Paten			fice conne		ewith.		applic	ation a	and tra	nsact	
Jack J. Janko	ovitz				42,690							
Correspondence	Addres	s: Direct al	l commu	nications a	about the	applica	ation	to:				
Customer N	lumber	Туре С	ustomer	Number H	Here			>	Numl	e Custo ber Ba I Here	omer r Code	
OR Firm or	Γ			· · · · · ·								
X Individual Name	Ratner	& Prestia										
Address	P.O. B	ox 980								-		
Address											,	
City	Valley	Forge				State	e	PA		Zip	19482	
Country											•	
Telephone	(610)	407-0700				Fax		(610)	407-0	701		
I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine and imprisonment, or both, under 18 U.S.C. 1 001, and that such willful false statements may jeopardize the validity of the application, any patent issuing thereon, or any patent to which this declaration is directed.												
Full name of per	son sign	ing (given	name, far	mily name))		-					
Dr. Osamu Yama			· ·									
Signature				Date								
Address of Assi	gnee 100 Osa	6, Oaza Kadom ika, 571 Japan	a, Kadoma-sł	ni					,			
Patentee Thiow Keng Tan			Citizenship Malaysia									
Residence/Post			lock 553,	Choa Chu	Kang No	rth 6, 1	1-08		aysia			
Patentee							Citiz	enshi	p			
Residence/Post	Office A	ddress				. 1						

REGISTERED PRACTITIONER INFORMATION (Supplemental Sheet)

Name	Registration Number	Name	Registration Number
Kevin R. Casey	32,117		Number
Benjamin E. Leace	33,412		
James C. Simmons	24,842		
Lawrence E. Ashery	34,515		
Christopher R. Lewis	36,201		
Robert L. Andersen	25,771		
Daniel N. Calder	27,424		
Louis W. Beardell, Jr.	40,506		
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Jonathan H. Spadt	45,122		
Mark J. Marcelli	38,040		
Joshua L. Cohen	42,690	^ ~	
Jack J. Jankovitz	34,608		
Kevin W. Goldstein	42,621		
Christopher I. Halliday	26,277		
Paul D. Golian	33,602		
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Bruce M. Monroe	28,028		
Rex A. Donnelly, IV	42,866		
Costas Krikelis			

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REISSUE APPLICATION BY THE INVENTOR,

Docket Number (Optional)

OFFER TO SURRENDER PATE	MTS-880US2
This is part of the application for a reissue patent ba	sed on the original patent identified below.
Name of Patentee(s) Thiow Keng Tan	
Patent Number 5,825,421	Date Patent Issued October 20, 1998
Title of invention VIDEO CODING METHOD AND DE	CODING METHOD AND DEVICES THEREOF
I am the inventor of the original patent.	
I offer to surrender the original patent.	
1. X Filed herein is a certificate under 37 CFR	3.73(b).
2. Ownership of the patent is in the inventor been made.	(s), and no assignment of the patent has
One of boxes 1 or 2 above must be checked.	
The written consent of all assignees owning an und this application for reissue.	vided interest in the original patent is included in
Signature	Date
Typed or printed name	
Thiow Keng Tan	
The assignee owning an undivided interest in said or and the assignee consents to the accompanying app	
I hereby declare that all statements made herein of n statements made on information and belief are believ were made with the knowledge that willful false state fine or imprisonment, or both, under 18 U.S.C. 1001 a jeopardize the validity of the application, any patent i declaration is directed.	red to be true; and further that these statements ments and the like so made are punishable by and that such willful false statements may
Name of assignee	
Matsushita Electric Industrial Co., Ltd. Signature of person signing for assignee	Data
	Date
Typed or printed name and title of person signing for a	assignee
Dr. Osamu Yamazaki Di	rector

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REISSUE APPLICATION BY THE ASSIGNEE,
OFFER TO SURRENDER PATENT

Docket Number (Optional)

OFFER TO SURRENDER PAT	ENT MTS-880US2
This is part of the application for a reissue patent ba	sed on the original patent identified below.
Name of Patentee(s):	
Thiow Keng Tan	
Patent Number	Date Patent Issued
5,825,421	October 20, 1998
Title of Invention VIDEO CODING METHOD AND THEREOF	D DECODING METHOD AND DEVICES
Matsushita Electric Industrial Co , Ltd. is the assi	gnee of the entire interest in the original patent.
I offer to surrender the original patent.	
X A certificate under 37 CFR 3.73(b) is attached	4
X A certificate under 37 CFR 3.73(b) is attached	J.
I am authorized to act on behalf of the assignee.	
I hereby declare that all statements made herein of n statements made on information and belief are believ were made with the knowledge that willful false state fine or imprisonment, or both, under 18 U.S.C. 1001 and the product of	yed to be true; and further that these statements ments and the like so made are punishable by and that such willful false statements may
jeopardize the validity of the application, any patent is declaration is directed.	ssued thereon, or any patent to which this
Name of assignee	
Matsushita Electric Industrial Co., Ltd.	
Signature of person signing for assignee	Date
Typed or printed name and title of person signing for a	assignee
Dr. Osamu Yamazaki	Director

Burden Hour Statement: This form is estimated to take 0.1 hours to complete. Time will vary depending upon the needs of the individual case. Any comments on the amount of time you are required to complete this form should be sent to the Chief Information Officer, Patent and Trademark Office, Washington, DC 20231. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Assistant Commissioner for Patents, Washington, DC 20231.

ASSENT BY ASSIGNEE FOR FILING OF REISSUE APPLICATION

This is part of the application for a reissue patent filed herewith based on the original patent identified as follows:

Name of Patentee Matsushita Electric Industrial Co, Ltd.

Patent Number: 5,825,421

61. 3,023,421

Date Patent Issued October 20, 1998

Title of Invention: VIDEO CODING METHOD AND DECODING METHOD

AND DEVICES THEREOF

I am an assignee owning an undivided interest to the above original patent.

I assent to the accompanying application for reissue.

Attached is a "Certificate under 37 C F.R. section 3.73(b)"

Matsushita Electric Industrial Co, Ltd.		
	Date:	
Signature of person signing for assignee		

Dr. Osamu Yamazaki Director

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant: T. Tan

: Art Unit:

Serial No.: To Be Assigned

: Examiner:

Filed:

Herewith

FOR:

VIDEO CODING METHOD AND

DECODING METHOD AND DEVICES

THEREOF

CERTIFICATE UNDER 37 CFR 3.73 (b)

Assistant Commissioner for Patents Washington, D.C. 20231

SIR:

Matsushita Electric Industrial Co., Ltd., a Japanese Corporation certifies that it is the assignee of the entire right, title and interest in the patent application identified above by virtue of an assignment from the inventor of the patent application identified above. The assignment was recorded in the Patent and Trademark Office at Reel 8607, Frame 0024, for which a copy thereof is attached.

The undersigned has reviewed all the documents in the chain of title of the patent application identified above and, to the best of undersigned's knowledge and belief, title is in the assignee identified above.

The undersigned (whose title is supplied below) is empowered to act on behalf of the assignee.

I hereby declare that all statements made herein of my own knowledge are true, and that all statements made on information and belief are believed to be true; and further, that these statements are made with the knowledge that willful false statements, and the like so made, are punishable by fine or imprisonment, or both, under Section 1001, Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

Date	:	
Name	:Dr. Osamu Yamazaki	
Title	:Director	
Signature	:	



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[P.3][[使获者的][[]]。

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NUMBER OF PAGES: 3

BRIEF: ASSIGNMENT OF ASSIGNOR'S INTEREST (SEE DOCUMENT FOR DETAILS).

ASSIGNOR:

TAN, THIOW KENG

DOC DATE: 03/03/1997

ASSIGNEE:

MATSUSHITA ELECTRIC INDUSTRIAL CO., LTD. 1006, OAZA KADOMA, KADOMA-SHI OSAKA, JAPAN 571

SERIAL NUMBER: 08773574

PATENT NUMBER:

FILING DATE: 12/27/1996

ISSUE DATE:

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ASSIGNMENT

	11001011111				
	WHEREAS, the ASSIGNOR, comprising the following named inventor(s)				
	Inventor(s)				
ASSIGNOR(s)/	1. Tan, Thiow Keng	2.			
INVENTOR(s)	3	4			
	has made an invention entitled:				
	VIDEO CODING METHOD AND DEC	CODING METHOD AND DEVICES THEREOF			
	and has executed an application concurrently herewith;	for Letters Patent of the United States			
ASSIGNEE	WHEREAS, the ASSIGNEE Matsushita Electric Industria_ Co., Ltd.				
(Full Name and address)	of 1006, Oaza Kadoma,	Kadoma-shi, Osaka 571 JAPAN			

is desirous of acquiring the entire interest in and to said invention and the Letters Patent to be obtained therefor,

NOW, THEREFORE, in consideration of the payment by ASSIGNEE to ASSIGNOR of a sum corresponding to One Dollar (\$1.00), and for other good and valuable consideration, the receipt of which is hereby acknowledged, ASSIGNOR, intending to be legally bound, hereby sells, assigns and transfers to ASSIGNEE, its successors and assigns the full and exclusive right, title and interest in and to said invention, all applications for Letters Patent for said invention, including all divisions and continuations thereof, all rights to claim priority based thereon, and all Letters Patent, including reissues, to be obtained therefor, including any and all foreign patent rights in this invention corresponding thereto.

ASSIGNOR hereby warrants that no assignment, sale, agreement or encumbrance has been or will be made or entered into which would conflict with this Assignment.

ASSIGNOR agrees it shall be legally bound, upon request of the ASSIGNEE or its successors or assigns or a legal representative thereof, to supply all information and evidence of which the ASSIGNOR has knowledge or possession, relating to the making and practice of said invention, to testify in any legal proceeding relating thereto, to execute all instruments proper to patent the invention in the United States of America and foreign countries in the name of the ASSIGNEE, and to execute all instruments proper to carry out the intent of this instrument.

If the invention requires a biological deposit, ASSIGNOR also grants to ASSIGNEE such control over any deposit made by ASSIGNOR as may be necessary to the validity of the patent rights assigned herein.

ASSIGNOR authorizes ASSIGNOR's attorney to insert at the end hereof the serial number and filing date of the aforesaid application for United States Letters Patent and/or the Attorney docket or file designation for this application.

If the ASSIGNOR includes more than one individual, these obligations shall apply to these individuals both individually and collectively.

IN WITNESS WHEREOF, this Assignment is executed on the day indicated below.

(Typed or Printed Name)	(Signat	(Signature)			(Date)			
1. Tan, Thiow Keng	Turn bu	astar.	March	3,	<u> 199</u> 7			
2	***************************************							
3								
4	*							
Application for United State	es Letters Patent							
Serial No. 08/773,574.		FiledDecember	er 27.	199)6			
Attorney Docket No.	MTS-850		_					

SIGNATURE

.